



## GENERAL INFORMATION

Data of the subject	
Subject name	Dynamic Systems
Subject code	DEA-GITI-313
Main program	<a href="#">Bachelor's Degree in Engineering for Industrial Technologies</a>
Involved programs	Grado en Ingeniería en Tecnologías Industriales y Grado en Administración y Dirección de Empresas [Third year] Grado en Ingeniería en Tecnologías Industriales [Third year]
Level	Reglada Grado Europeo
Quarter	Semestral
Credits	6,0 ECTS
Type	Obligatoria (Grado)
Department	Department of Electronics, Control and Communications
Coordinator	Ramón Rodríguez Pecharromán
Schedule	See web
Office hours	Send e-mail to get an appointment
Course overview	Introduction to Dynamic Systems. Modeling and analysis in both time and frequency domains of LTI systems.

Teacher Information	
<b>Teacher</b>	
Name	Julio de San Sebastián Soria
Department	Department of Electronics, Control and Communications
E-Mail	jdesansebastian@icai.comillas.edu
<b>Teacher</b>	
Name	José María Urretavizcaya González
Department	Department of Electrical Engineering
E-Mail	jmurretavizcaya@icai.comillas.edu
<b>Teacher</b>	
Name	Juan Luis Zamora Macho
Department	Department of Electronics, Control and Communications
Office	Alberto Aguilera 25 [D-212]
E-Mail	Juanluis.Zamora@iit.comillas.edu
Phone	2420
<b>Teacher</b>	
Name	Alberto Azañón Montero
Department	Department of Electronics, Control and Communications



<b>E-Mail</b>	aazanon@icai.comillas.edu
<b>Profesores de laboratorio</b>	
<b>Teacher</b>	
<b>Name</b>	Carlos Javier de Vicente Peña
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	cjdevicente@icai.comillas.edu
<b>Teacher</b>	
<b>Name</b>	Antonio González Elías
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	agelias@icai.comillas.edu
<b>Teacher</b>	
<b>Name</b>	Emilio Manuel Domínguez Adan
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	emdominguez@comillas.edu
<b>Teacher</b>	
<b>Name</b>	Jesús Julián Calvo Herrando
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	jjcalvo@icai.comillas.edu
<b>Teacher</b>	
<b>Name</b>	Johel Jose Rodriguez D'Derlee
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	jjrodriguez@icai.comillas.edu
<b>Teacher</b>	
<b>Name</b>	Jose María Cogollor Delgado
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	jmccogollor@icai.comillas.edu
<b>Teacher</b>	
<b>Name</b>	Mónica Rodríguez Cortina
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	mrcortina@icai.comillas.edu
<b>Teacher</b>	
<b>Name</b>	Pablo Carlos del Saz-Orozco Huang
<b>Department</b>	Department of Electronics, Control and Communications
<b>E-Mail</b>	pcdelsazorozco@icai.comillas.edu

## DESCRIPTION OF THE SUBJECT

### Contextualization of the subject

#### Prerequisites

Basic knowledge of Physics, electric and electronic circuits and mechanical systems.

## Course contents

### Contents

#### FUNDAMENTALS

##### 1. INTRODUCTION TO DYNAMIC SYSTEMS

- 1.1 Concept of system, signal and model.
- 1.2 Model applications.
- 1.3 Properties of models and systems.
- 1.4 Modeling of Linear-Time-Invariant (LTI) Systems.

##### 2. LAPLACE TRANSFORM

- 2.1 Uses of the Laplace Transform.
- 2.2 Definition of the Laplace Transform.
- 2.3 Properties of the Laplace Transform.
- 2.4 Laplace Transform of basic functions.
- 2.5 Inverse Laplace Transform.
- 2.6 Relationship between poles and time response.
- 2.7 Determination of the time response from the differential equation.
- 2.8 Classification of time-response terms.

##### 3. TRANSFER FUNCTION

- 3.1 Forced and natural responses.
- 3.2 Transfer Function definition.
- 3.3 Stability.
- 3.4 Routh-Hurwitz stability criterion.
- 3.5 Steady state: DC gain and frequency response.
- 3.6 Block diagrams.



## REAL-WORLD SYSTEM MODELING. ANALYSIS OF LOW-ORDER SYSTEMS

### 4. REAL-WORLD SYSTEM MODELING

- 4.1 Electric circuits.
- 4.2 Electronic circuits based on operational amplifiers.
- 4.3 Translational mechanical systems.
- 4.4 Rotational mechanical systems.
- 4.5 Thermal systems.

### 5. FIRST-ORDER SYSTEMS

- 5.1 First-order systems.
- 5.2 Step response of first-order systems.
- 5.3 Frequency response: the Bode diagram.
- 5.4 Bode diagram of first order systems.
- 5.5 Asymptotic Bode diagram of systems composed of first-order terms.
- 5.6 Relationship between time response and frequency response.

### 6. SECOND-ORDER SYSTEMS

- 6.1 Second-order systems.
- 6.2 Time response of second-order systems.
- 6.3 Influence of an additional pole or zero to the standard second-order system.
- 6.4 Bode diagram of a second-order system.
- 6.5 Bode diagram of higher-order systems.

## LABORATORY

### LAB PROJECTS

- P1. Analysis and simulation tools for dynamic systems: Matlab and Simulink.
- P2. Design and analysis of second-order filters based on a Sallen-Key circuit setup, in both the time and the frequency domains.

## EVALUATION AND CRITERIA

Evaluation activities	Evaluation criteria	Weight
Mid-term and final exams (individual)	<ul style="list-style-type: none"><li>• Understanding concepts.</li><li>• Problem solving.</li><li>• Problem-solving results assesment.</li><li>• Writing.</li></ul>	65



Continuous evaluation quizzes (individual)	<ul style="list-style-type: none"><li>• Understanding concepts.</li><li>• Problem solving.</li><li>• Problem-solving results assesment.</li></ul>	10
Lab sessions (group)	<ul style="list-style-type: none"><li>• Understanding concepts.</li><li>• Lab sessions performance.</li><li>• Lab sessions results assesment.</li><li>• Teamworking skill.</li><li>• Writing</li></ul>	25

## Grading

### ORDINARY

In the ordinary period grading is composed of:

- Final exam: 45%. A minimum grade of 5 is required on the final exam to pass the course.
- Mid-term exam: 20%.
- Continuous evaluation quizzes: 10%
- Lab: 25%. A minimum grade of 5 is required to pass the course.

In case of failing, the re-take exam may include both theory and lab contents.

### EXTRAORDINARY (RE-TAKE) EXAM

In the re-take exam grading is composed of:

- Re-take exam: 55%. A minimum grade of 5 is required on the final exam to pass the course.
- Mid-term exam: 15%.
- Continuous evaluation quizzes: 5%
- Lab: 25%. A minimum grade of 5 is required to pass the course.

### ATTENDANCE RULES

Class attendance is mandatory, according to the Academic Regulations of the Higher Technical School of Engineering (ICAI). The requirements of attendance will be applied independently for theory and laboratory sessions:

- In the case of theory sessions, failure to comply with this rule may prevent the student from taking the exam in the ordinary period.
- In the case of laboratory sessions, failure to comply with this rule may prevent the student from taking the exam both in the normal and in the re-take periods.
- In any case, unjustified absences from laboratory sessions will be penalized in the grading.

## BIBLIOGRAPHY AND RESOURCES

### Basic References

- Notes provided by the instructor in the course web page.
- N. S. Nise. Control Systems Engineering, 8th Edition. Wiley. 2019.

In compliance with current regulations on the **protection of personal data**, we would like to inform you that you may consult the aspects related to privacy and data that you have accepted on your registration form by entering this website and clicking on "download"

<https://servicios.upcomillas.es/sedelectronica/inicio.aspx?csv=02E4557CAA66F4A81663AD10CED66792>